

ROBA®-slip hubs

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ROBA® – a Well-known Trade Name

ROBA[®]-slip hub the load-holding, frictionally-locking safety clutch

ROBA[®] is a trade name which has been the symbol of quality and experience in clutch construction for decades. A comprehensive range of torque limiters has originated from the robust jaw clutch (ROBA[®]-safety slip clutch).

ROBA[®]-slip hub devices are simple to use. The torque table makes it possible to set the torque according to a scale and offers considerably simplified installation. ROBA[®]-slip hub devices are reasonably-priced drive elements which protect machinery and equipment against costly damage, and against downtimes resulting from time-consuming repairs.

As a result of their high-strength materials and careful manufacture with optimum utilisation of space, ROBA[®]-slip hub devices are smaller than similar clutches on the market. Twelve different designs and combinations are available. We have a solution for all drive units. However, if any of your wishes remain unanswered, please contact us.

ROBA® stands for: trust in safety.

Application

ROBA[®]-slip hub devices are used as overload protection for machine drives with chain sprockets, toothed wheels or pulleys. The ROBA[®]- slip hub is used wherever expensive and sensitive motors, gearboxes or machinery components need to be protected against overloads. If overload occurs, the drive element slips and, therefore, limits the torque.

ROBA[®]-slip hub devices are used in packing machines, transport systems and equipment, construction machinery, textile machinery, agricultural machinery, mechanical handling equipment, feed units, loading systems, in equipment for the chemical industry and in machinery and equipment in general industrial engineering.

Asbestos-free friction linings with

a large surface area and a low wear rate ensure a long lifetime.

The bearing bushing

width can be shortened to suit the width of the drive element.

The short, robust hub

ensures compact overall dimensions for the complete slip hub, together with easy assembly and fitting.

The set screw

applies pressure onto the keyway of the shaft, preventing axial movement of the slip hub.

A speed monitor

(available on request) prevents excessively long drive element slippage or serves on the output to monitor the chain drive against breakage.

Design

Despite their simple construction, ROBA®-slip hub devices are high-quality machine components. The ROBA®-slip hub is fully machined and phosphated and, therefore, protected against rust. It is a fully enclosed construction, so that dirt is prevented from reaching internal components.

The ROBA[®]-slip hub, which is a rotating component, fits very easily into all drive systems as a result of its smooth construction. It is particularly suitable for attachment to the outside of machines and for those systems which must be kept clean easily, e.g. in the food industry.

ROBA[®]-slip hub devices are designed in such a way that they can be adapted very easily to the most varied of working conditions, e.g. high slipping frequency and low torque or low friction work and extremely high torque, as well as all intermediate stages of torque and friction work, and the desired lifetime.

Positive-locking torque adjustment

securement via the lock washer and the locking screw to prevent the adjusting nut loosening

Four wide claws

engage in the keyways of the hub and guarantee reliable torque transmission even under impact loads or reversing load conditions.

Adjusting nut together

with a graduation scale for simple torque adjustment and wear re-adjustment

Cup springs with

low characteristic curve keep torque reduction due to wear low. Alternative spring layerings ensure a wide torque range per size.

Fig. 1 Type 100.110



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1. Hub

1. Hub

 Thrust washer
 Cup springs
 Friction linings
 Bearing bushing
 Cup spring supporting bolt
 Chain sprocket
 Adjusting nut 0

Thrust washer
 Adjusting nut 0
 Locking screw
 Cup springs
 Friction linings
 Bearing bushing
 Adjusting screw
 Chain sprocket
 Lock washer

Functional Description

Part List Sizes 0 – 5

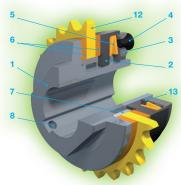


Fig. 2 Type 100.110, Sizes 0 - 5

Part List Sizes 6 – 12

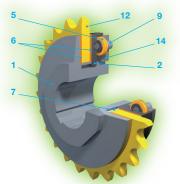


Fig. 3 Type 100.110, Sizes 6 – 12

Function

The drive element (12) (chain sprocket or V-belt disk) is placed on the bushing (7) as shown in Figure 2 and clamped between the friction linings (6) with the aid of the thrust washer (2), the cup springs (5) and the adjusting nut (3) with the lock washer (13). The more powerfully the cup springs (5) are compressed by the adjusting nut (3), the higher the torque at which the drive element (12) slips. The precise torque adjustment operation is described on page 21.

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in special design up to 200.000 Nm	
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It should also be noted that the difference in torque after friction lining wear is lowest with single cup spring layering and highest with triple cup spring layering. In addition, a torque adjustment in the uppermost quarter of the maximum torques gives a particularly even adjustment (the spring characteristic curve has its smallest increase in this area). Other friction linings are also available for special applications (see further details on page 19).

The $\ensuremath{\mathsf{ROBA}}\xspace^{\ensuremath{\mathsf{\$}}\xspace}$ -slip hub is available for three different torque ranges.

Rule of thumb:

ROBA[®]-slip hub for **high friction work and low torque** (single-layer cup springs, single contact force).

ROBA[®]-slip hub for **medium friction work and higher torque (double**layer cup springs, double contact force).

ROBA[®]-slip hub for **low friction work** and very high torque (triple-layer cup springs, triple contact force).



Please observe the operating speed or slipping speed (see Explanation on page 19)!

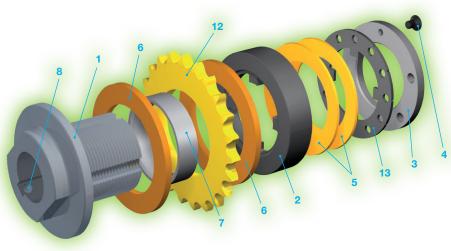


Fig. 4 Type 100.110, Sizes 0 - 5



ROBA®-slip hubs Summary of Constructional Designs

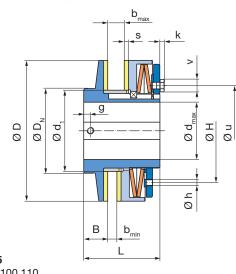
ROBA [®] - slip hub standard	Torque: 2 to 50.000 Nm Sizes 0 to 12 Type 100	 Safety clutch for machine drives requiring protection against overload. When the preset overload torque is reached, the drive element slips, preventing damage to the drive system.
ROBA [®] -slip hub with standard chain sprocket	Torque: 6 to 1.400 Nm Sizes 01 to 5 Type 100	 Slip hub complete with chain sprocket as a reasonably- priced drive element with a high safety factor for all chain drives
ROBA [®] -slip hub with rustproof friction linings	Torque: 6 to 2.400 Nm Sizes 01 to 6 Type 1002_	For drives in open air installations, particularly wet ambient conditions or for long downtimes Page 9
ROBA [®] -Co-Pro [®]	Torque: 5 to 1.500 Nm Sizes 30 to 50 Type 10001000 Type 10101000	Compact, high performance safety clutch Hub designs: Design M Type 10001000 Design L Type 10101000 Page 10
ROBA [®] -clamp	Torque: 2 to 400 Nm Sizes 0 to 2 Type 106	 For shaft ends without a keyway. Enables easy and fast shaft installation. The keyless slip hub is better suited to larger shafts than the standard design.
ROBA®-min	Torque: 8 to 1.100 Nm Sizes 1 to 5 Type 121 Type 123	 For drive elements with particularly small diameters and very large installation widths Larger installation width than Type 100, but only capable of transmitting lower torques Hub designs: short hub Type 121 long hub Type 123



ROBA[®]-slip hub standard

Type 100.___ Sizes 0 to 12

Sizes 0 to 5 Types 100.1_ _, 100.2_ _ and 100.3_ _



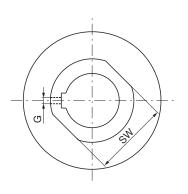
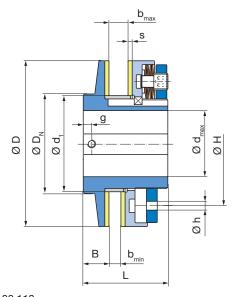


Fig. 5 Type 100.110

Sizes 6 to 12 Types 100.1_ _ and 100.2_ _



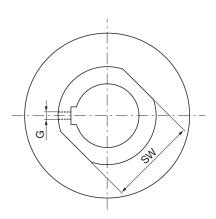


Fig. 6 Type 100.110

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ROBA®-slip hub standard

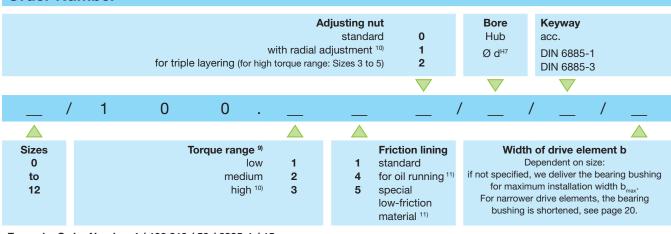
Technical Data (Sizes 0 to 5)				Size											
	Sizes 0 to 5)			0	01	1	2	3	4	5					
	Type 100.11_	M _G	[Nm]	2 - 10	6 - 30	14 – 70	26 - 130	50 - 250	110 - 550	140 - 700					
Limit torques	Type 100.21_	M _G	[Nm]	10 - 20	30 - 60	70 - 130	130 – 250	250 - 550	550 - 1100	700 – 1400					
for overload	Туре 100.3	ype 100.3_ M_ [Nm		18 - 30	60 - 90	130 – 200	250 - 400	-	-	-					
	Type 100.3_2	M _G	[Nm]	-	-	-	-	550 - 800	1100 – 1600	1400 – 2100					
Operating speed ¹⁾		n _{max}	[rpm]	8500	6600	5600	4300	3300	2700	2200					
Weight (pilot bored)			[kg]	0.3	0.6	0.9	1.6	3.1	5.4	9.0					

We reserve the right to make dimensional and constructional alterations.

Technical Data (Size											
		6	7	8	9	10	11	12					
Limit torques	Type 100.11_	M _G	[Nm]	240-1200	400-2000	680-3400	1200-6000	2000-10000	3400-17000	5000-25000			
for overload	overload Type 100.21_		[Nm]	1200-2400	2000-4000	3400-6800	6000-12000	10000-20000	17000-34000	25000-50000			
Operating speed ¹⁾		n _{max}	[rpm]	1900	1600	1300	1100	920	780	690			
Weight (pilot bored)			[kg]	12.4	21.2	30.7	79	125	179	278			

Dim. [mm]		в	l b _{min}	o b _{max}	D	D _N	d ₁ ^{H8 8)}	d _{min}	d d _{max}	G	g	н	h	k	L	sw	s	u	v
	0	8,5	2	6	45	45	35	7	20 2)	M4	3	37	3	_ 7)	33	-	2,5	37	2 7)
	01	16	3	8	58	40	40	12	22	3)	4	46	5	_ 7)	45	32	3	46	2,5 7)
	1	17	3	10	68	45	44	12	25	4)	5	50	5	1,3 ⁷⁾	52	41	3	50	3 7)
	2	19	4	12	88	58	58	15	35	5)	5	67	6	3	57	50	3	67	10
	3	21	5	15	115	75	72	19	45	6)	5	84	6	5,5	68	65	4	84	13
	4	23	6	18	140	90	85	25	55	M8	6	104	7	5,5	78	80	4	97	13
Size	5	29	8	20	170	102	98	30	65	M8	8	125	8	5,5	92	90	5	109	13
Size	6	31	8	23	200	120	116	40	80	M8	8	150	10	-	102	105	5	-	-
	7	33	8	25	240	150	144	48	100	M10	8	185	10	-	113	135	5	-	-
	8	35	8	25	285	180	170	60	120	M10	8	230	10	-	115	165	5	-	-
	9	53	12	28	350	225	237	57	140	M12	9	290	10	-	162	220	6	-	-
	10	60	15	35	415	255	270	80	160	M12	9	340	10	-	185	250	6	-	-
	11	73	20	45	490	285	305	90	180	M16	11	400	10	-	222	280	7	-	-
	12	79	25	55	555	315	335	100	200	M16	11	450	10	-	250	310	7	-	-

Order Number



Example: Order Number 4 / 100.210 / 50 / 6885-1 / 15

1) See Explanations page 19

- 2) Size 0: up to Ø 19 keyway acc. DIN 6885-1
- over Ø 19 keyway acc. DIN 6885-3

3) Size 01: up to Ø 12 M4, over Ø 12 M5

4) Size 1: up to Ø 12 M4, over Ø 12 up to Ø 17 M5, over Ø 17 M6

5) Size 2: up to Ø 17 M5, over Ø 17 M6

6) Size 3: up to Ø 22 M6, over Ø 22 M8

- 7) Hexagon socket countersunk screw to ISO 10642/DIN 7991
- 8) Tolerance value H8 refers to output element bore.
 9) See Technical Data, limit torque for overload M₆

10) Only Sizes 0 to 5

11) For available torques, see Table 1, page 19



Technical Explanations

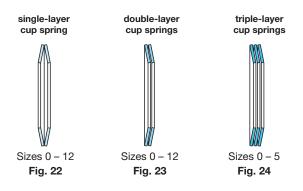
Torques – Cup Spring Layering

The cup spring layering in Figs. 22 – 24 show our ROBA[®]-slip hub standard design. Each layering results in a different spring characteristic curve or spring force (torque). A rule of thumb when using ROBA[®]-slip hubs is:

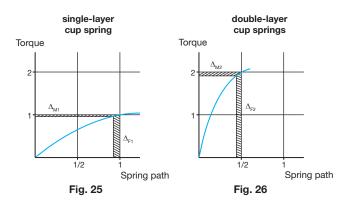
 $\mathsf{ROBA}^{\circledast}\text{-slip}$ hub for high friction work and low torque; single-layer cup spring.

ROBA[®]-slip hub for medium friction work and larger torques; doublelayer cup springs.

ROBA®-slip hub for low friction work and very high torques; triple-layer cup springs.



The torque behaviour of the ROBA®-slip hub on friction lining wear is clearly shown in Figs. 25 and 26. With single cup spring layering, the torque reduction on wear is very low (Fig. 25). With double cup spring layering, the change in torque is larger (Fig. 26), and with triple cup spring layering, the torque reduction is highest. However, the cup springs are designed with a relatively flat characteristic curve so that large wear paths can occur without larger drops in torque.



For special applications, weaker cup springs are available for the individual slip hub sizes, with which the minimum torques can be under-run.

Other cup spring layerings can be produced (e.g. combinations of double and single-layering) individually for special applications. In Figs. 25 and 26 it is shown that a torque adjustment in the uppermost quarter of the spring characteristic curve (torque) produces a particularly even torque, as the spring characteristic curve has its smallest increase in this area.



The torques stated in the Table "Technical Data" refer to drive elements made of steel or cast iron!

During the start-up phase (matching the friction surfaces), after long downtimes and during or after long slipping occurrences, the friction lining wear pattern and the friction coefficiencies may change. This can lead to changes in torque.

Friction Linings

As shown in Table 1 below, four different friction linings are available. The torque and the speed values in the slip hub catalogue are applicable for the standard friction lining during dry running. For other friction linings, please find the correct values in Table 1 or ask the manufacturers for special application values.

Friction lining number	Application	Available torque from M _{max.}
1	standard for dry running	100 %
2	rustproof friction pairing	100 %
4	bronze friction lining for oil running	30 %
5	special low-friction material (only for single-layer cup spring layering and with reduced friction)	50 %

Table 1

Speeds

The ROBA®-slip hub is thermically loaded depending on the slipping speed, slip time and the set torque.

To make sure that the ROBA®-slip hub friction linings are not overheated or destroyed, the specified friction parameters must not be exceeded.

The recommended values in the Reference Values Diagram (Diagram 1) show the maximum slipping speed limits of the standard friction linings in dry running.

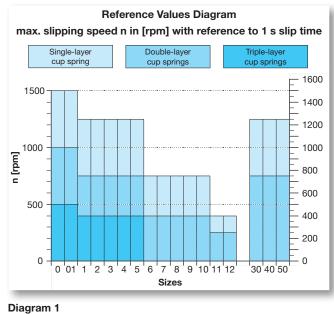
These speed limits refer to a maximum slip time of 1 second. For longer slip times, the slipping speed must be reduced.

If in doubt, please carry out the friction work calculations for the respective application.



If the permitted slipping duration is exceeded, the ROBA®-slip hub will be overloaded. => Destruction of the friction linings

A speed monitor prevents the drive elements slipping for an excessively long time. Please ask the manufacturers for devices adapted to your application.



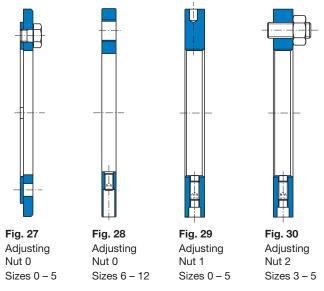
¹⁹



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Technical Explanations

Adjusting Nuts



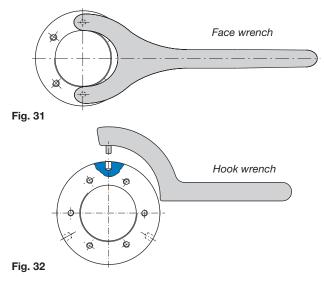
The standard adjusting nut for Sizes 0 - 5 (adjusting nut 0, Fig. 27) is adjusted using a face wrench (Fig. 31). The adjusting nut is secured using a lock washer with four projections as well as a hexagon head screw which is screwed through the adjusting nut into the lock washer bores.

The standard adjusting nut for Sizes 6 - 12 (adjusting nut 0, Fig. 28) has no lock washer. It is secured against twisting with a radial set screw.

Additionally, we provide an adjusting nut for radial adjustment for Sizes 0 - 5. Adjustment takes place here using a hook wrench (Fig. 32). On this design (adjusting nut 1, Fig. 29), the thrust washer must be shortened. The device is additionally secured against twisting using a radial screw-in set screw, which is pressed into one of the four hub keyways.

For triple-layering on the ROBA®-slip hub Sizes 0 - 2, the adjusting nut 0 or 1 is used. On Sizes 3 – 5, the adjusting nut 2 is used (Fig. 30). The adjusting nut 2 for the ROBA®-slip hub varies from the adjusting nut 0 or 1 for the ROBA®-slip hub as it has six axial set screws for torque adjustment. As with adjusting nut 1, it is secured using a radial set screw.

For high torque adjustments, it may be necessary to lengthen the lever on the face wrench or hook wrench (e.g. extension using a pipe).



Bearing Bushing

If the drive element installation width is not specified on order, we deliver the bearing bushing (Fig. 33) for the maximum installation width (b_{max}). If a smaller installation width is required, the bearing bushing must be shortened accordingly on the end without the inner chamfer, see the Example below. The bearing bushing is to be installed with the inner chamfer facing forwards, see Fig. 33.

Example for s	hortening the	bearing bushing:	*
---------------	---------------	------------------	---

•	-	-	•
ROBA®-slip hub, Siz	ze 3, Type	100.210 (see	e page 7)
Drive element =	chain spro	ocket disk	3/4" x 1/2", z = 23,
	chain spro	ocket width	B ₁ = 12,7 mm
Bearing bushing wid	th I [mm] a	ccording to t	he formula below:
I = b + 1.5 . s + 0.5			
$I = 12.7 + 1.5 \cdot 4 + 0$).5		
l = 19.2 _{-0.2} mm			
	* The	total length of	the clutch is not affected.

Bearing bushing width:

I =	b + 1.5	i∙s+	0.5	[mm]		standarc e 1001	l friction 0	pairing			
I ₁ =	$I_1 = b + 1.5 \cdot s + 2 \cdot s_1 + 0.5$					for rustproof friction pa Type 10020					
I =	b + 2 ·	s+f		[mm]	for	Type 10_	_01000				
I I ₁ S S ₁ f	[mm] [mm] [mm] [mm] [mm]	= = = =	bearing bush bearing bush friction linings maximum ins (nominal dimu Friction lining see page 10 Strength of ru Dimension fo	ing width s (see pag stallation v ension + f strength for Type ustproof c	for sli ge 9) width tolerai (see 10_0. lisk (s	ip hubs wi for drive el nce) page 7 for 1000) ee page 9	th rustproc lements Type 100				
			nner chamfer Bearing		J	Size 30 40 50	Type 1000 -0.5 -1.5 -1.5	f Type 1010 +5.5 +4.5 +4.5			
Fig.	. 33							Table 2			

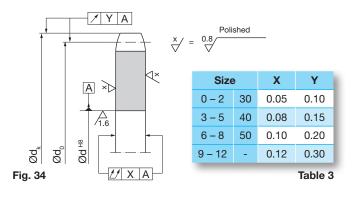
Fig. 33

For high radial load and high slipping frequency, we recommend the ROBA®-slip hub with needle bearing Type 160 (page 14).

Maintenance – Installation

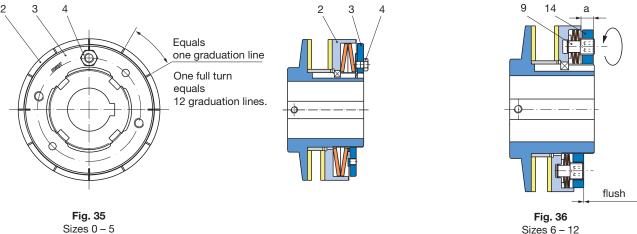
Due to its smooth construction, the ROBA®-slip hub is easy to clean. As the friction linings wear down, the ROBA®-slip hub must be readjusted or, if they are very worn, the friction linings must be replaced. Apart from this, the ROBA®-slip hub needs no maintenance.

During installation, please ensure that no grease or oil comes into contact with the friction surfaces. In the area of the friction surfaces, the drive element surface must be finely polished and have exactly plane parallel surfaces (see Fig. 34 and Table 3).





Torque Adjustment





On the ROBA®-slip hub devices Sizes 1 – 5, the rear side of the thrust washer (Item 2) is engraved with 12 markings (24 markings on Size 0), and the adjusting nut (Item 3) is engraved with four markings (see Fig. 35).

The adjusting nut with locking washer is adjusted by hand up to the contact on the cup springs. The four notches on the adjusting nut and the notches on the thrust washer must align. Then the adjusting nut should be turned by the number of graduation lines which equal the required torque.

An Adjustment Table (Fig. 37) is adhered to the clutch, from which the number of graduation lines necessary for the required torque can be read off. If a required torque value lies between two graduation lines, please adjust to the smaller value (positive spring force tolerance). After the torque adjustment has been made, please secure the adjusting nut by turning the locking screw (Item 4).

On ROBA®-slip hub devices Sizes 6 - 12, the dimension "a" (see Fig. 36) can be found in the adhered Table (Fig. 38) and can be adjusted accordingly (see Fig. 36) using the adjusting nut (Item 14).

Finally, the cup spring supporting bolts (Item 9) should be turned stepwise evenly approx. 1/4 turn until they are flush with the adjusting nut (Item 14).

	ROBA [®] -slip hub	up tract, jrads.	Single CS	Torque	Nm	50	62	80	100	130	150	200	235	250
mayr®	Size 3	s cont u	ר <i>י</i> רן א י רן	Graduation lines	GL	9	10	12	14	16	18	20	22	24
	Surface-ground chain sprocket	grads		Torque	Nm	250	295	340	375	420	450	480	520	550
D-87665 Mauerstetten Made in Germany	for friction lining No. 1, run-in condition	Tu then of th 12 1	۲ <i>۱</i> ۲۲	Graduation lines	GL	10	11	12	13	14	15	16	17	18

Fig. 37

	ROBA®-slip hub	a ਜ →⊔+	Single	M [Nm]	240	300	420	540	660	780	900	1020	1140	1200
mayr	Size 6		Cup Spring	a =	14.9	14.8	14.4	14.0	13.6	13.2	12.7	12.2	11.7	11.4
power transmission D-87665 Mauerstetten	Surface-ground chain sprocket		Double	M [Nm]		600	840	1080	1320	1560	1800	2040	2280	2400
Made in Germany	for friction lining No. 1, run-in condition	Spring bolt flush	Cup Spring	a =		12.6	12.4	12.2	12.0	11.8	11.6	11.4	11.1	10.9

Fig. 38

The ROBA®-slip hub with triple cup spring layering has no Adjustment Table adhered to it.

Torque adjustment is carried out in the following way:

Please tighten the adjusting nut without using a lot of force. Then adjust the individual screws in the adjusting nut evenly in approx. 1/4 turns to the specified dimensions "b" or "a" shown in the Adjustment Diagram (if necessary, please order the Table from the manufacturers). In this way the required torque is obtained.

For initial adjustment, the ROBA®-slip hub should slip several times at 50 % of the torque specified in the Catalogue, in order to achieve a clean wear pattern on the friction lining.

Depending on the slipping frequency, occasional re-adjustment is necessary due to friction lining wear.

The ROBA®-slip hub can of course be delivered complete with a drive element at extra cost, pre-adjusted to the set torque.



For clutch Types with no adhered Adjustment Table, feel free to ask the manufacturers for Adjustment Diagrams.



Installation Examples

ROBA®-slip hub standard

Type 100.110

Features

Simple, robust and reasonably priced torque limitation for protection against overload damages.

Application

Protection of drives with narrow drive elements, e.g. single chain sprocket.

Technical Details

Axial attachment onto the shaft is carried out via a press cover and a screw, screwed into the central thread of the shaft. Slip monitoring is carried out by a speed monitor (available on request) with an external initiator.

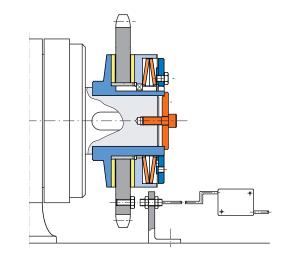


Fig. 39

ROBA®-slip hub with needle bearing

Type 160.210

Features

Needle bearing in place of the standard bearing bushing; suitable for continuous slipping at low speeds and torques.

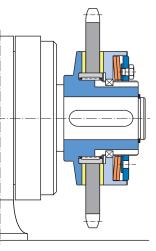
Application

Drives with high radial loads, high slipping frequency and increased shaft run-out accuracy.

Technical Details

Axial attachment onto the shaft is carried out via a set screw and a press cover, or, as indicated in the drawing, via a locking ring.

The width of the drive element is not variable due to the fixed needle bearing length.



ROBA®-slip hub with rustproof friction lining

Type 100.220

Features

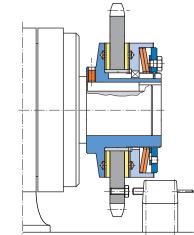
Slip hub with disks made of stainless steel to prevent the friction linings rusting.

Application

Overload protection for machines operating in open air conditions, in particularly wet conditions or machines subject to long downtimes.

Technical Details

The slip hub is held on the shaft via a set screw which applies pressure onto the keyway. The rustproof disks do not adhere to the friction lining and do not form rust compounds. A speed monitor (available on request) prevents excessively long slippage on overload.



ROBA[®]-min

Fig. 40

Type 121.210

Features

Slip hub with a standard friction lining and a small bronze friction lining on the hub collar side.

Application

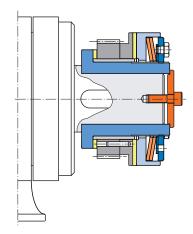
For drive elements with very small outer diameters and large installation widths.

Technical Details

The hub collar and a friction lining are significantly reduced.

On the side with the standard friction lining, an intermediate flange is additionally attached between lining and drive element and pinned to the drive element.

Fig. 42



22



Installation Examples

ROBA®-max

Type 170.110

Features

Slip hub with a long hub, the transmittable torques correspond to the standard ${\rm ROBA}^{\circledast}\mbox{-slip}$ hub.

Application

For very wide drive elements, e.g. multiple-row-chain sprockets.

Technical Details

The ROBA®-max can take drive elements with a large width range. The bearing bushing is modified to the required installation width. Attachment onto the shaft is carried out via a set screw which applies pressure onto the keyway.

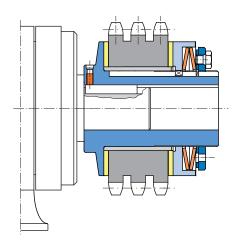


Fig. 43

ROBA®-LD - torsionally rigid

Type 134.110

Features

Slip hub combined with a torsionally rigid flexible allsteel coupling (ROBA®-D coupling).

Application

Overload protection, connection of two shafts and shaft misalignment compensation with low torsional backlash torque transmission.

Technical Details

The slip hub is attached using a press cover. The ROBA®-D hub is attached using a set screw onto the shaft. The ROBA®-D coupling transmits the torque backlash-free. Low torsional backlash results from the thrust washer jaw backlash in the slip hub outer keyways.

ROBA®-lastic

Type 131.110

Features

Slip hub for connection of two shafts with polygon-shaped, highly flexible rubber elements.

Application

Overload protection, connection of two shafts in drives with large shaft misalignments, impacts and torsional vibrations.

Technical Details

The slip hub is attached onto the shaft using a press cover. The flexible coupling hub sits without attachment frictionally-locked on the shaft. Torque transmission takes place via a rubber element which has a high misalignment compensation capability and damps torsional vibrations and impacts.

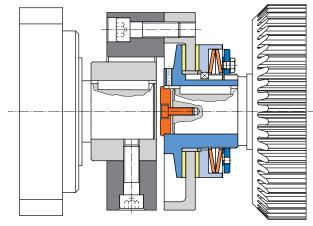


Fig. 44

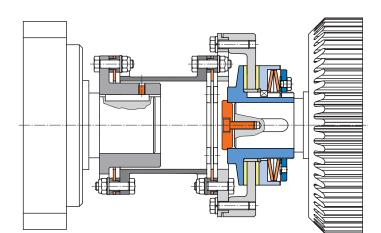


Fig. 45